

General Description

The MAX5122/MAX5123 low-power, 12-bit, voltage-out-put, digital-to-analog converters (DACs) feature an internal precision bandgap reference and output amplifier.

The MAX5122 operates on a single +5V supply with an internal +2.5V reference, and offers a configurable output amplifier. If necessary, the user can override the on-chip, <10ppm/°C voltage reference with an external reference. The MAX5123 has the same features as the MAX5122 but operates from a single +3V supply and has an internal +1.25V precision reference. The user-accessible inverting input and output of the amplifier allows specific gain configurations, remote sensing, and high output drive capability for a wide range of force/sense applications. Both devices draw only $500\mu A$ of supply current, which reduces to $3\mu A$ in power-down mode. In addition, their power-up reset feature allows for a user-selectable initial output state of either 0V or midscale and reduces output glitches during power-up.

The serial interface is compatible with SPI™, QSPI™, and MICROWIRE™, which makes the MAX5122/MAX5123 suitable for cascading multiple devices. Each DAC has a double-buffered input organized as an input register followed by a DAC register. A 16-bit shift register loads data into the input register. The DAC register may be updated independently or simultaneously with the input register.

Both devices are available in a 16-pin QSOP package and are specified for the extended-industrial (-40°C to +85°C) operating temperature range. For pin-compatible 14-bit upgrades, see the MAX5171/MAX5173 data sheet; for the pin-compatible 13-bit version, see the MAX5132/MAX5133 data sheet.

Applications

Industrial Process Control

Automatic Test Equipment

Digital Offset and Gain Adjustment

Motion Control

Microprocessor-Controlled Systems

SPI and QSPI are trademarks of Motorola, Inc.
MICROWIRE is a trademark of National Semiconductor Corp.

Features

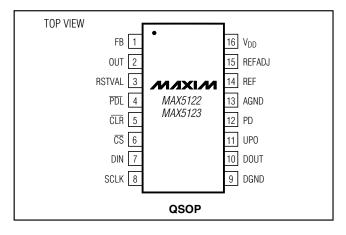
- **♦ Single-Supply Operation**
 - +5V (MAX5122)
 - +3V (MAX5123)
- ♦ Built-In 10ppm/°C max Precision Bandgap Reference
 - +2.5V (MAX5122)
 - +1.25V (MAX5123)
- ♦ SPI/QSPI/MICROWIRE-Compatible, 3-Wire Serial Interface
- Pin-Programmable Shutdown Mode and Power-Up Reset (0 or Midscale Output Voltage)
- ♦ Buffered Output Capable of Driving 5kΩ | 100pF or 4–20mA Loads
- ♦ Space-Saving 16-Pin QSOP Package
- Pin-Compatible 13-Bit Upgrades Available (MAX5132/MAX5133)
- Pin-Compatible 14-Bit Upgrades Available (MAX5171/MAX5173)

Ordering Information

| PART | PIN- PACKAGE | INL (LSB) | PKG CODE |
|-------------|-----------------|--------------|-------------|
| MAX5122AEEE | 16 QSOP | ±0.5 | E16-5 |
| MAX5122BEEE | 16 QSOP | ±1 | E16-5 |
| MAX5123AEEE | 16 QSOP | ±1 | E16-5 |
| MAX5123BEEE | 16 QSOP | ±2 | E16-5 |

Note: All devices are specified over the -40°C to +85°C operating temperature range.

Pin Configuration



Maxim Integrated Products 1

ABSOLUTE MAXIMUM RATINGS

| V _{DD} to AGND, DGND | |
|-------------------------------------|-----------------------------|
| AGND to DGND | 0.3V to +0.3V |
| Digital Inputs to DGND | |
| Digital Outputs (DOUT, UPO) to DGND | $0.3V$ to $(V_{DD} + 0.3V)$ |
| FB, OUT to AGND | $0.3V$ to $(V_{DD} + 0.3V)$ |
| REF, REFADJ to AGND | $0.3V$ to $(V_{DD} + 0.3V)$ |
| Maximum Current into Any Pin | 50mA |

| Continuous Power Dissipation ($T_A = +70^{\circ}C$) | |
|---|----------------|
| QSOP (derate 8.00mW/°C above +70°C) | 667mW |
| Operating Temperature Range | 40°C to +85°C |
| Storage Temperature Range | 65°C to +150°C |
| Lead Temperature (soldering, 10s) | +300°C |

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS—MAX5122 (+5V)

 $(V_{DD} = +5V \pm 10\%, AGND = DGND, 33nF capacitor at REFADJ, internal reference, R_L = 5k\Omega, C_L = 100pF, output amplifier configured in unity-gain, T_A = T_{MIN}$ to T_MAX, unless otherwise noted. Typical values are at T_A = +25°C.)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|------------------------------------|--------------------|--|-------|-------|-------|---------|
| STATIC PERFORMANCE | • | | | | | |
| Resolution | N | | 12 | | | Bits |
| Integral Nanlingovity (Nata 1) | INII | MAX5122A | -0.5 | | 0.5 | - LSB |
| Integral Nonlinearity (Note 1) | INL | MAX5123B | -1 | | 1 | LSB |
| Differential Nonlinearity | DNL | | -1 | | 1 | LSB |
| Offset Error (Note 2) | Vos | | -10 | | 10 | mV |
| Gain Error | GE | | -3 | -0.2 | 3 | mV |
| Full-Scale Temperature | TCVFS | MAX5122A | | 3 | 10 | nnm/°C |
| Coefficient (Note 3) | TOVES | MAX5123B | | 10 | 30 | ppm/°C |
| Power-Supply Rejection Ratio | PSRR | 4.5V ≤ V _{DD} ≤ 5.5V | | 20 | 250 | μV/V |
| REFERENCE | | | | | | 1 |
| Output Voltage | V _{REF} | T _A = +25°C | 2.475 | 2.5 | 2.525 | V |
| Output Voltage Temperature | TCV _{REF} | MAX5122A | | 3 | | ppm/°C |
| Coefficient | ICAKEL | MAX5122B | | 10 | | ppin/ C |
| Reference External Load Regulation | Vout/Iout | 0 ≤ I _{OUT} ≤ 100μA (sourcing) | | 0.1 | 1 | μV/μΑ |
| Reference Short-Circuit Current | | | | 4 | | mA |
| REFADJ Current | | REFADJ = V _{DD} | | 3.3 | 7 | μΑ |
| DIGITAL INPUT | | | · | | | |
| Input High Voltage | VIH | | 3 | | | V |
| Input Low Voltage | VIL | | | | 0.8 | V |
| Input Hysteresis V _{HYS} | | | | 200 | | mV |
| Input Leakage Current | I _{IN} | $V_{IN} = 0 \text{ or } V_{DD}$ -1 0.001 | | 0.001 | 1 | μΑ |
| Input Capacitance | CIN | | | 8 | | pF |
| DIGITAL OUTPUTS | • | | | | | • |
| Output High Voltage | Voн | ISOURCE = 2mA VDD - 0.5 | | | V | |
| Output Low Voltage | V _{OL} | ISINK = 2mA | | 0.13 | 0.4 | V |

ELECTRICAL CHARACTERISTICS—MAX5122 (+5V) (continued)

 $(V_{DD} = +5V \pm 10\%, AGND = DGND, 33nF$ capacitor at REFADJ, internal reference, $R_L = 5k\Omega$, $C_L = 100pF$, output amplifier configured in unity-gain, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $T_A = +25$ °C.)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|-----------------|---|------|----------------------|-----|--------|
| DYNAMIC PERFORMANCE | • | | | | | |
| Voltage Output Slew Rate | SR | | | 0.6 | | V/µs |
| Output Settling Time | | To ±0.5LSB, V _{STEP} = 2.5V | | 20 | | μs |
| Output Voltage Swing (Note 4) | | | | 0 to V _{DD} | | V |
| Current into FB | | | -0.1 | 0 | 0.1 | μΑ |
| Time Required to Exit Shutdown | | | | 2 | | ms |
| Digital Feedthrough | | $\overline{\text{CS}} = \text{V}_{\text{DD}}, \text{f}_{\text{SCLK}} = 100\text{kHz},$ $\text{V}_{\text{SCLK}} = 5\text{Vp-p}$ | | 5 | | nV-sec |
| POWER REQUIREMENTS | | | | | | |
| Power-Supply Voltage (Note 5) | V _{DD} | | 4.5 | | 5.5 | V |
| Power-Supply Current (Note 5) I _{DD} | | | | 500 | 600 | μΑ |
| Power-Supply Current in Shutdown | ISHDN | | | 3 | 20 | μΑ |

ELECTRICAL CHARACTERISTICS—MAX5123 (+3V)

 $(V_{DD} = +3V \pm 10\%, AGND = DGND, 33nF$ capacitor at REFADJ, internal reference, $R_L = 5k\Omega$, $C_L = 100pF$, output amplifier connected in unity-gain, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$.)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|------------------------------------|--------------------|---|----------|------|-------|-----------|
| STATIC PERFORMANCE | | | <u> </u> | | | |
| Resolution | N | | 12 | | | Bits |
| Integral Nanlingarity (Note 1) | INL | MAX5123A | -1 | | 1 | LSB |
| Integral Nonlinearity (Note 1) | IINL | MAX5123B | -2 | | 2 | LOD |
| Differential Nonlinearity | DNL | | -1 | | 1 | LSB |
| Offset Error (Note 2) | Vos | | -10 | | 10 | mV |
| Gain Error | GE | | -5 | -0.2 | 5 | mV |
| Full-Scale Temperature | TCVFS | MAX5123A | | 3 | 10 | ppm/°C |
| Coefficient (Note 3) | TOVES | MAX5123B | | 10 | 30 | ррпі, С |
| Power-Supply Rejection Ratio | PSRR | 2.7V ≤ V _{DD} ≤ 3.3V | | 20 | 250 | μV/V |
| REFERENCE | • | | | | | |
| Output Voltage | V _{REF} | T _A = +25°C | 1.237 | 1.25 | 1.263 | V |
| Output Voltage Temperature | TCV _{REF} | MAX5123A | | 3 | | ppm/°C |
| Coefficient | TOVREF | MAX5123B | | 10 | | Трріпі, С |
| Reference External Load Regulation | Vout/Iout | 0 ≤ I _{OUT} ≤ 100μA (sourcing) | | 0.1 | 1 | μV/μΑ |
| Reference Short-Circuit Current | | | | 4 | | mA |
| REFADJ Current | | REFADJ = V _{DD} | | 3.3 | 7 | μΑ |
| DIGITAL INPUT | | | | | | • |
| Input High Voltage | | | 2.2 | | | V |
| Input Low Voltage V _{IL} | | | | | 0.8 | V |
| Input Hysteresis | VHYS | | | 200 | | mV |

ELECTRICAL CHARACTERISTICS—MAX5123 (+3V) (continued)

 $(V_{DD} = +3V \pm 10\%, AGND = DGND, 33nF capacitor at REFADJ, internal reference, R_L = 5k\Omega, C_L = 100pF, output amplifier connected in unity-gain, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C.)$

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|----------------------------------|--------|---|-----------------------|----------------------|-----|--------|
| Input Leakage Current | liN | V _{IN} = 0 or V _{DD} | -1 | 0.001 | 1 | μΑ |
| Input Capacitance | CIN | | | 8 | | pF |
| DIGITAL OUTPUTS | • | | | | | 1 |
| Output High Voltage | Voн | ISOURCE = 2mA | V _{DD} - 0.5 | 5 | | V |
| Output Low Voltage | VoL | I _{SINK} = 2mA | | 0.13 | 0.4 | V |
| DYNAMIC PERFORMANCE | | | | | | |
| Voltage Output Slew Rate | SR | | | 0.6 | | V/µs |
| Output Settling Time | | To ±0.5LSB, V _{STEP} = 1.25V | | 20 | | μs |
| Output Voltage Swing (Note 4) | | | | 0 to V _{DD} | | V |
| Current into FB | | | -0.1 | 0 | 0.1 | μΑ |
| Time Required to Exit Shutdown | | | | 2 | | ms |
| Digital Feedthrough | | $\overline{\text{CS}} = \text{V}_{\text{DD}}, \text{f}_{\text{SCLK}} = 100\text{kHz}, \\ \text{V}_{\text{SCLK}} = 3\text{Vp-p}$ | | 5 | | nV-sec |
| POWER REQUIREMENTS | | | | | | • |
| Power-Supply Voltage (Note 5) | VDD | | 2.7 | | 3.6 | V |
| Power-Supply Current (Note 5) | IDD | | | 500 | 600 | μΑ |
| Power-Supply Current in Shutdown | ISHDN | | | 3 | 20 | μΑ |

TIMING CHARACTERISTICS—MAX5122 (+5V)

 $(V_{DD} = +5V \pm 10\%, AGND = DGND, 33nF capacitor at REFADJ, internal reference, R_L = 5k\Omega, C_L = 100pF, output amplifier connected in unity-gain, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C.)$

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|--------------------------------------|---------------------------|-----|-----|-----|-------|
| SCLK Clock Period | tcp | | 100 | | | ns |
| SCLK Pulse Width High | tcH | | 40 | | | ns |
| SCLK Pulse Width Low | t _{CL} | | 40 | | | ns |
| CS Fall to SCLK Rise Setup Time | tcss | | 40 | | | ns |
| SCLK Rise to CS Rise Hold Time | SCLK Rise to CS Rise Hold Time tCSH | | | | | ns |
| SDI Setup Time | t _{DS} | | 40 | | | ns |
| SDI Hold Time | tDH | | 0 | | | ns |
| SCLK Rise to DOUT Valid Propagation Delay Time | t _{DO1} | C _{LOAD} = 200pF | | | 80 | ns |
| SCLK Fall to DOUT Valid Propagation Delay Time | | C _{LOAD} = 200pF | | | 80 | ns |
| SCLK Rise to CS Fall Delay Time | tCS0 | | 10 | | | ns |
| CS Rise to SCLK Rise Hold Time | K Rise Hold Time t _{CS1} 40 | | | | ns | |
| CS Pulse Width High | tcsw | | 100 | | | ns |

TIMING CHARACTERISTICS—MAX5123 (+3V)

 $(V_{DD} = +3V \pm 10\%, AGND = DGND, 33nF capacitor at REFADJ, internal reference, R_L = 5k\Omega, C_L = 100pF, output amplifier connected in unity-gain, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C.)$

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|--|---------------|-----|-----|-----|-------|
| SCLK Clock Period | tcp | | 150 | | | ns |
| SCLK Pulse Width High | tcH | | 75 | | | ns |
| SCLK Pulse Width Low | t _{CL} | | 75 | | | ns |
| CS Fall to SCLK Rise Setup Time toss 60 | | | | | | ns |
| SCLK Rise to CS Rise Hold Time | tcsh | | 0 | | | ns |
| SDI Setup Time t _{DS} | | | 60 | | | ns |
| SDI Hold Time | tDH | | 0 | | | ns |
| SCLK Rise to DOUT Valid Propagation Delay Time | tDO1 | CLOAD = 200pF | | | 200 | ns |
| SCLK Fall to DOUT Valid Propagation Delay Time | $\frac{1}{1}$ that $\frac{1}{1}$ Character 200nF | | | 200 | ns | |
| SCLK Rise to CS Fall Delay Time | tcso | | 10 | | | ns |
| CS Rise to SCLK Rise Hold Time | tcs1 | | 75 | | | ns |
| CS Pulse Width High | tcsw | | 150 | | | ns |

Note 1: Accuracy is guaranteed by the following table:

| V _{DD} | Accuracy Guaranteed | | | | | |
|-----------------|---------------------|----------|--|--|--|--|
| (V) | From Code: | To Code: | | | | |
| 5 | 16 | 4095 | | | | |
| 3 | 33 | 4095 | | | | |

Note 2: Offset is measured at the code closest to 10mV.

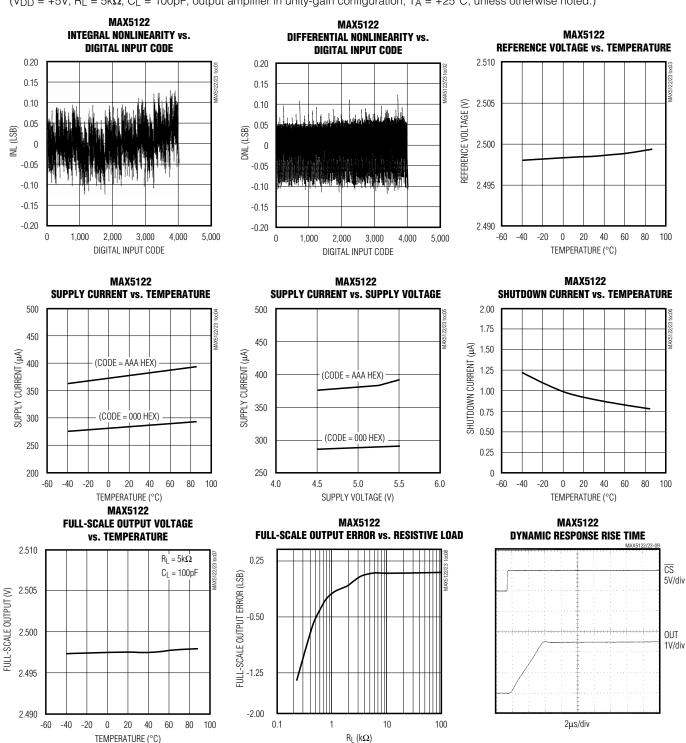
Note 3: The temperature coefficient is determined by the "box" method, in which the maximum ΔV_{OUT} over the temperature range is divided by ΔT and the typical reference voltage.

Note 4: Accuracy is better than 1.0LSB for VouT = 10mV to (VDD - 180mV). Guaranteed by PSR test on end points.

Note 5: $R_{LOAD} = \infty$ and digital inputs are at either V_{DD} or DGND.

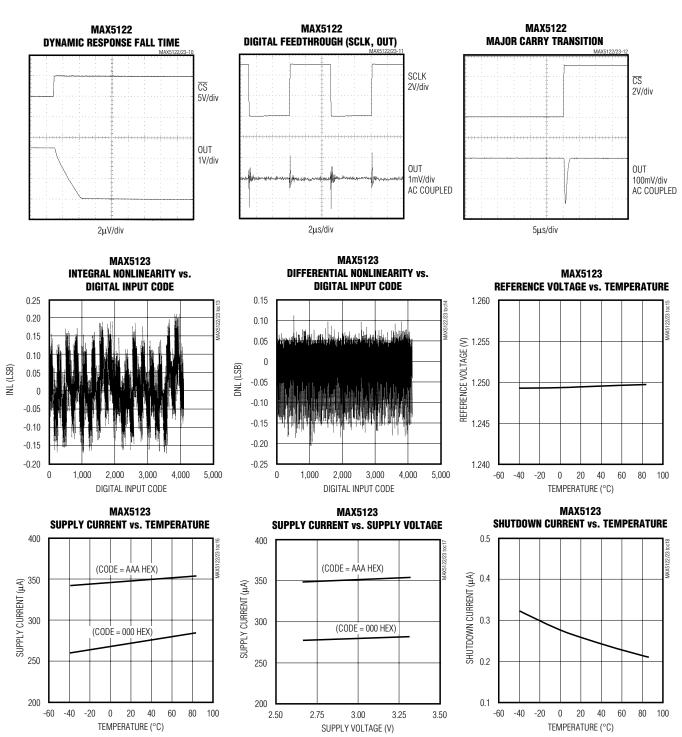
Typical Operating Characteristics

 $(V_{DD} = +5V, R_L = 5k\Omega, C_L = 100pF, output amplifier in unity-gain configuration, T_A = +25°C, unless otherwise noted.)$



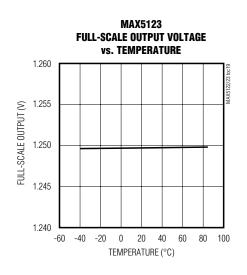
Typical Operating Characteristics (continued)

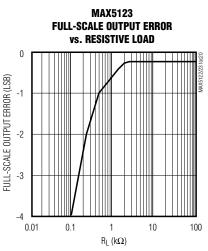
 $(V_{DD} = +5V, R_L = 5k\Omega, C_L = 100pF, output amplifier in unity-gain configuration, T_A = +25°C, unless otherwise noted.)$

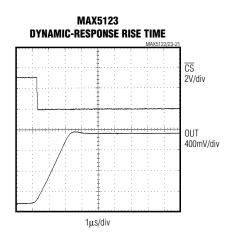


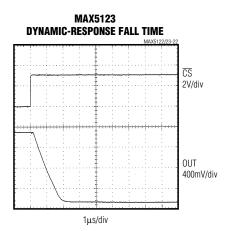
Typical Operating Characteristics (continued)

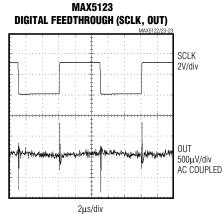
 $(V_{DD} = +5V, R_L = 5k\Omega, C_L = 100pF, output amplifier in unity-gain configuration, T_A = +25°C, unless otherwise noted.)$

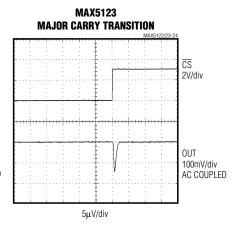












Pin Description

| PIN | NAME | FUNCTION |
|-----|-----------------|---|
| 1 | FB | Amplifier Inverting Sense Input (Analog Input) |
| 2 | OUT | Analog Output Voltage. High impedance if part is in shutdown. |
| 3 | RSTVAL | Reset Value Input (Digital Input). 1: Connect to V _{DD} to select midscale as the output reset value. 0: Connect to DGND to select 0V as the output reset value. |
| 4 | PDL | Power-Down Lockout (Digital Input). 1: Normal operation. 0: Disallows shutdown (device cannot be powered down). |
| 5 | CLR | Reset DAC Input (Digital Input). Clears the DAC to its predetermined (RSTVAL) output state. Clearing the DAC will cause it to exit a software shutdown state. |
| 6 | CS | Active-Low Chip-Select Input (Digital Input) |
| 7 | DIN | Serial Data Input. Data is clocked in on the rising edge of SCLK. |
| 8 | SCLK | Serial Clock Input |
| 9 | DGND | Digital Ground |
| 10 | DOUT | Serial Data Output |
| 11 | UPO | User-Programmable Output (Digital Output) |
| 12 | PD | Power-Down Input (Digital Input). Pulling PD high when $\overline{PDL} = V_{DD}$ places the IC into shutdown with a maximum shutdown current of 20 μ A. |
| 13 | AGND | Analog Ground |
| 14 | REF | Buffered Reference Output/Input. In internal reference mode, the reference buffer provides a +2.5V (MAX5122) or +1.25V (MAX5123) nominal output, externally adjustable at REFADJ. In external reference mode, disable the internal reference by pulling REFADJ to V _{DD} and applying the external reference to REF. |
| 15 | REFADJ | Analog Reference Adjust Input. Bypass with a 33nF capacitor to AGND. Connect to V _{DD} when using an external reference. |
| 16 | V _{DD} | Positive Power Supply. Bypass with a 0.1µF capacitor in parallel with a 4.7µF capacitor to AGND. |
| | | |

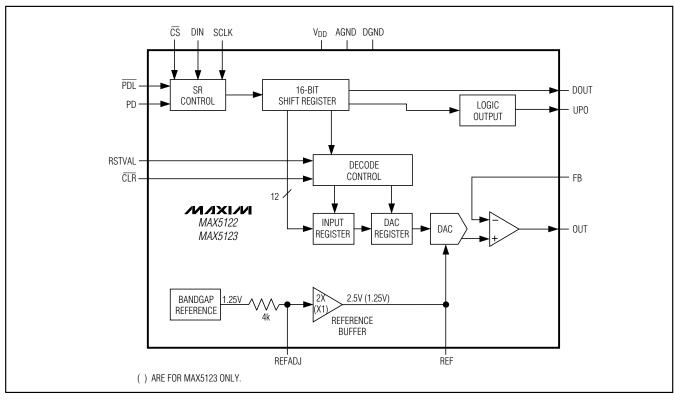


Figure 1. Simplified Functional Diagram

Detailed Description

The MAX5122/MAX5123 12-bit, force/sense DACs are easily configured with a 3-wire serial interface. They include a 16-bit data-in/data-out shift register and have a double-buffered digital input consisting of an input register and a DAC register. In addition, these devices employ precision bandgap references, as well as an output amplifier with accessible feedback and output pins that can be used to set the gain externally (Figure 1) or for forcing and sensing applications. These DACs are designed with an inverted R-2R ladder network (Figure 2) that produces a weighted voltage proportional to the digital input code.

Internal Reference

Both devices use an on-board precision bandgap reference with a low temperature coefficient of only 10ppm/°C (max) to generate an output voltage of +2.5V (MAX5122) or +1.25V (MAX5123). The REF pin can source up to 100µA and may become unstable with capacitive loads exceeding 100pF. REFADJ can be used for minor adjustments to the reference voltage.

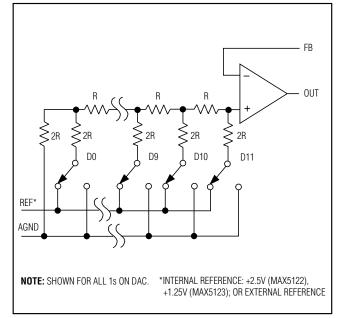


Figure 2. Simplified Inverted R-2R DAC Structure

The circuit in Figure 3 achieves a nominal reference adjustment range of $\pm 1\%$. Connect a 33nF capacitor from REFADJ to AGND to establish low-noise DAC operation. Larger capacitor values may be used, but will result in increased start-up delay. The time constant (τ) for the start-up delay is determined by the REFADJ input impedance of $4k\Omega$ and C_{REFADJ} :

 $\tau = 4k\Omega \cdot C_{REFADJ}$

External Reference

An external reference may be applied to the REF pin. Disable the internal reference by pulling REFADJ to V_{DD} . This allows an external reference signal (AC- or DC-based) to be fed into the REF pin. For proper operation, **do not** exceed the input voltage range limits of 0 to $(V_{DD}$ - 1.4V) for V_{REF} .

Determine the output voltage using the following equation (REFADJ = V_{DD}):

where NB is the numeric value of the MAX5122/MAX5123 input code (0 to 4095), VREF is the external reference voltage, and G is the gain of the output amplifier, set by an external resistor-divider. The REF pin has a minimum input resistance of $40 \text{k}\Omega$ and is code-dependent.

Output Amplifier

The MAX5122/MAX5123's DAC output is internally buffered by a precision amplifier with a typical slew rate of 0.6V/µs. Access to the output amplifier's inverting input (FB) provides the user greater flexibility with amplifier gain setting and signal conditioning (see *Applications Information*).

The output amplifier typically settles to ± 0.5 LSB from a full-scale transition within 20µs when it is connected in unity gain and loaded with $5k\Omega \mid 100$ pF. Loads less than $1k\Omega$ may result in degraded performance.

Power-Down Mode

These devices feature software- and hardware-programmable (PD pin) shutdown modes that reduce the typical supply current to 3µA. To enter software shutdown mode, program the control sequence for the DAC as shown in Table 1.

In shutdown mode, the amplifier output becomes high-impedance and the serial interface remains active. Data in the input registers is saved, allowing the MAX5122/MAX5123 to recall the output state prior to entering shutdown when returning to normal operation. To exit shutdown mode, load both input and DAC registers simultaneously or update the DAC register from the input register. When returning from shutdown to normal operation, wait 2ms for the reference to settle. When using an external reference, the DAC requires only 20µs for the output to stabilize.

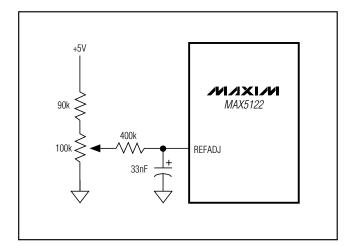


Figure 3a. MAX5122 Reference Adjust Circuit

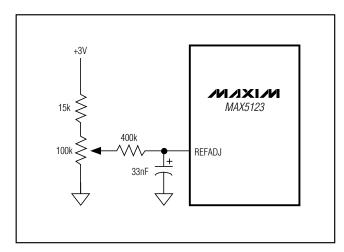


Figure 3b. MAX5123 Reference Adjust Circuit

Table 1. Serial-Interface Programming Commands

| | 16 | B-BIT SER | RIAL WORD | S0* | FUNCTION |
|----|----|-----------|-----------------|---|--|
| C2 | C1 | C0 | D11 D0 | S0* | FUNCTION |
| 0 | 0 | 0 | XXXXXXXXXXX | 0 No operation. | |
| 0 | 0 | 1 | 12-Bit DAC Data | Load input register; DAC register unchanged. | |
| 0 | 1 | 0 | 12-Bit DAC Data | 0 Simultaneously load input and DAC registers; exit shu | |
| 0 | 1 | 1 | XXXXXXXXXXX | 0 | Update DAC register from input register; exit shutdown. |
| 1 | 0 | 1 | XXXXXXXXXXX | 0 | Shutdown DAC (provided PDL = 1). |
| 1 | 0 | 0 | XXXXXXXXXXX | 0 | UPO goes low (default). |
| 1 | 1 | 0 | XXXXXXXXXXX | 0 | UPO goes high. |
| 1 | 1 | 1 | 1XXXXXXXXXXX | 0 | Mode 1; DOUT clocked out on SCLK's rising edge. |
| 1 | 1 | 1 | 00XXXXXXXXX | 0 | Mode 0; DOUT clocked out on SCLK's falling edge (default). |

X = Don't care * S0 is a sub-bit and always zero.

Power-Down Lockout Input (PDL)

The power-down lockout pin (PDL) disables shutdown when low. When in shutdown mode, a high-to-low transition on PDL will wake up the DAC with its output still set to the state prior to power-down. PDL can also be used to wake up the device asynchronously.

Power-Down Input (PD)

Pulling PD high places the MAX5122/MAX5123 in shutdown. Pulling PD low will not return the MAX5122/MAX5123 to normal operation. A high-to-low transition on PDL or appropriate commands (Table 1) via the serial interface are required to exit power-down mode.

Serial-Interface Configuration (SPI/QSPI/MICROWIRE/PIC16/PIC17)

The MAX5122/MAX5123 3-wire serial interface is compatible with SPI, QSPI, PIC16/PIC17 (Figure 4) and MICROWIRE (Figure 5) interface standards. The 2-byte-long serial input word contains three control bits, 12 data bits in MSB-first format, and one sub-bit, which is always zero (Table 2).

The MAX5122/MAX5123's digital inputs are double buffered, which allows the user to:

- Load the input register without updating the DAC register,
- Update the DAC register with data from the input register,
- Update the input and DAC registers concurrently.

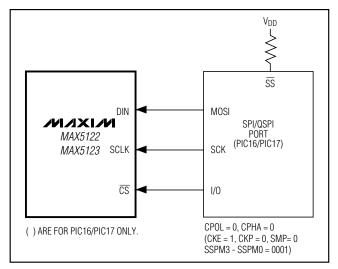


Figure 4. SPI/QSPI Interface Connections (PIC16/PIC17)

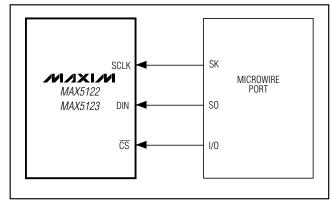


Figure 5. MICROWIRE Interface Connections

The 16-bit input word may be sent in two 1-byte packets (SPI-, MICROWIRE-, and PIC16/PIC17-compatible), with $\overline{\text{CS}}$ low during this period. The control bits C2, C1, and C0 (table 1) determine:

- The clock edge on which DOUT transitions,
- The state of the user-programmable logic output,
- The configuration of the device after shutdown.

The general timing diagram in Figure 6 illustrates how data is acquired. \overline{CS} must be low for the part to receive data. With \overline{CS} low, data at DIN is clocked into the register on the rising edge of SCLK. When \overline{CS} transitions high, data is latched into the input and/or DAC registers, depending on the setting of the three control bits C2, C1, and C0. The maximum serial clock frequency quaranteed for proper operation is 10MHz for the

Table 2. Serial Data Format

| MSB | | | LSB |
|--------------|------|-------------------|------------|
| ← | 16 B | ITS OF SERIAL DAT | A ⇒ |
| Control Bits | N | MSBData BitsLSB | Sub-Bit |
| C2, C1, C0 | С |)11D0 | S0 |

MAX5122 and 6.6MHz for the MAX5123. Figure 7 depicts a more detailed timing diagram of the serial interface.

PIC16 with SSP Module and PIC17 Interface

The MAX5122/MAX5123 are compatible with a PIC16/PIC17 microcontroller (μ C), using the synchronous serial port (SSP) module. To establish SPI communication, connect the controller as shown in Figure 4 and configure the PIC16/PIC17 as system master by initializing its synchronous serial port control register (SSP-CON) and synchronous serial port status register (SSPSTAT) to the bit patterns shown in Tables 3 and 4.

In SPI mode, the PIC16/PIC17 μ Cs allow eight bits of data to be synchronously transmitted and received simultaneously. Two consecutive 8-bit writings (Figure 6) are necessary to feed the DAC with three control bits, 12 data bits, and one sub-bit. DIN data transitions on the serial clock's falling edge and is clocked into the DAC on SCLK's rising edge. The first eight bits of DIN contain the three control bits (C2, C1, C0) and the first five data bits (D11–D7). The second 8-bit data stream contains the remaining bits (D6–D0), and the sub-bit S0.

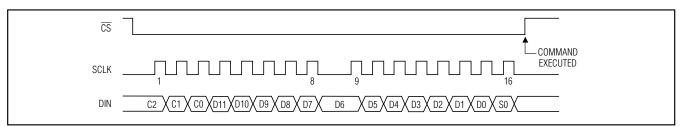


Figure 6. Serial-Interface Timing

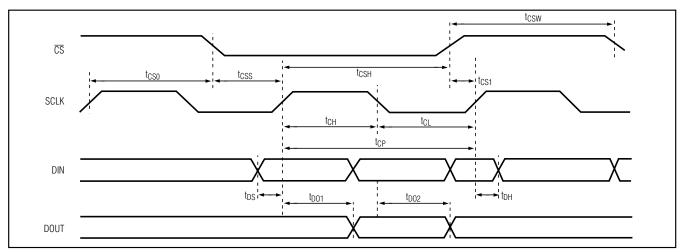


Figure 7. Detailed Serial-Interface Timing

Table 3. Detailed SSPCON Register Contents

| CONTROL BIT | | MAX5122/MAX5123 SETTINGS | SYNCHRONOUS SERIAL-PORT CONTROL REGISTER (SSPCON) | | |
|-------------|------|-----------------------------|---|--|--|
| WCOL | BIT7 | X | Write Collision Detection Bit | | |
| SSPOV | BIT6 | X | Receive Overflow Detect Bit | | |
| SSPEN | BIT5 | 1 | Synchronous Serial Port Enable Bit. 0: Disables serial port and configures these pins as I/O port pins. 1: Enables serial port and configures SCK, SDO and SCI as serial-port pins. | | |
| CKP | BIT4 | 0 | Clock Polarity Select Bit. CKP = 0 for SPI master-mode selection. | | |
| SSPM3 | BIT3 | 0 | | | |
| SSPM2 | BIT2 | 0 | Synchronous Serial Port Mode Select Bit. Sets SPI master mode | | |
| SSPM1 | BIT1 | 0 | and selects f _{CLK} = f _{OSC} / 16 | | |
| SSPM0 | BIT0 | 1 | | | |

X = Don't care

Table 4. Detailed SSPSTAT Register Contents

| CONT | ROL BIT | MAX5122/MAX5123 SETTINGS | SYNCHRONOUS SERIAL-PORT CONTROL REGISTER (SSPSTAT) | | |
|------|---------|--|---|--|--|
| SMP | BIT7 | 0 | SPI Data Input Sample Phase. Input data is sampled at the middle of the data output time. | | |
| CKE | BIT6 | SPI Clock Edge Select Bit. Data will be transmitted on the edge of the serial clock. | | | |
| D/A | BIT5 | X | Data Address Bit | | |
| Р | BIT4 | X | Stop Bit | | |
| S | BIT3 | X | Start Bit | | |
| R/W | BIT2 | X | Read/Write Bit Information | | |
| UA | BIT1 | X | Update Address | | |
| BF | BIT0 | X | Buffer Full Status Bit | | |

X = Don't care

Serial Data Output

The contents of the internal shift-register are output serially on DOUT which allows for daisy-chaining of multiple devices (see *Applications Information*) as well as data readback. The MAX5122/MAX5123 may be programmed to shift data out of DOUT on the serial clock's rising edge (Mode 1) or on the falling edge (Mode 0). The latter is the default during power-up and provides a lag of 16 clock cycles, maintaining SPI, QSPI, MICROWIRE, and PIC16/PIC17 compatibility. In Mode 1, the output data lags DIN by 15.5 clock cycles. During power-down, DOUT retains its last digital state prior to shutdown.

User-Programmable Output (UPO)

The UPO feature allows an external device to be controlled through the serial-interface setup (Table 1) thereby reducing the number of microcontroller I/O ports required. During power-down, this output will retain the last digital state before shutdown. With CLR pulled low, UPO will reset to the default state after wake-up.

Applications Information

Definitions

Integral Nonlinearity (INL)

Integral nonlinearity (Figure 8a) is the deviation of the values on an actual transfer function from a straight line. This straight line can be either a best-straight-line fit (closest approximation to the actual transfer curve) or a line drawn between the endpoints of the transfer function, once offset and gain errors have been nullified. For a DAC, the deviations are measured at every single step.

Differential Nonlinearity (DNL)

Differential nonlinearity (Figure 8b) is the difference between an actual step height and the ideal value of

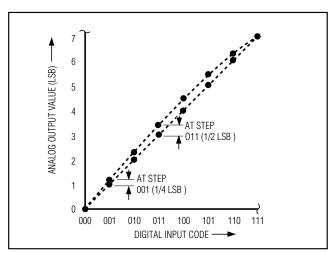


Figure 8a. Integral Nonlinearity

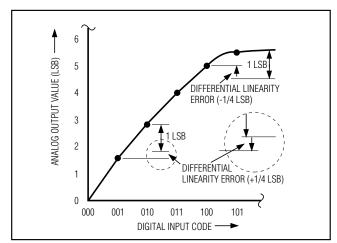


Figure 8b. Differential Nonlinearity

1LSB. If the magnitude of the DNL is less than or equal to 1LSB, the DAC guarantees no missing codes and is monotonic.

Offset Error

The offset error (Figure 8c) is the difference between the ideal and the actual offset point. For a DAC, the offset point is the step value when the digital input is zero. This error affects all codes by the same amount and can usually be compensated for by trimming.

Gain Error

Gain error (Figure 8d) is the difference between the ideal and the actual full-scale output voltage on the transfer curve, after nullifying the offset error. This error alters the slope of the transfer function and corresponds to the same percentage error in each step.

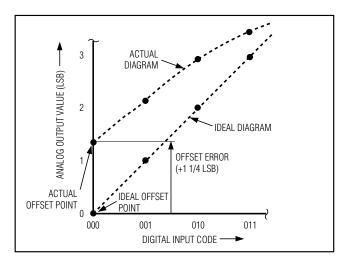


Figure 8c. Offset Error

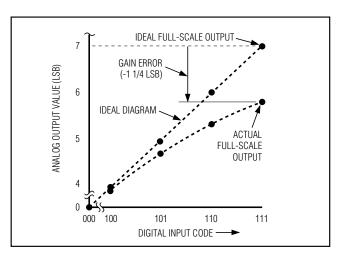


Figure 8d. Gain Error

Settling Time

The settling time is the amount of time required from the start of a transition until the DAC output settles to its new output value within the converter's specified accuracy.

Digital Feedthrough

Digital feedthrough is noise generated on the DAC's output when any digital input transitions. Proper board layout and grounding will significantly reduce this noise, but there will always be some feedthrough caused by the DAC itself.

Unipolar Output

Figure 9 shows the MAX5122/MAX5123 setup for unipolar, rail-to-rail operation with a closed-loop gain of 2V/V. With its internal reference of +2.5V, the MAX5122 provides a convenient unipolar output range of 0 to +4.99878V, while the MAX5123 offers an output range of 0 to +2.49939V with its on-board +1.25V reference. Table 5 lists example codes for unipolar output voltages.

Bipolar Output

The MAX5122/MAX5123 can be configured for unity-gain bipolar operation (FB = OUT) using the circuit shown in Figure 10. The output voltage VouT is then given by the following equation:

$$VOUT = VREF [{G (NB / 4096)} - 1]$$

where NB is the numeric value of the DAC's binary input code, VREF is the voltage of the internal (or external) precision reference, and G is the overall gain. The application circuit in Figure 10 uses a low-cost op amp (MAX4162) external to the MAX5122/MAX5123. Together with the MAX5122/MAX5123 this circuit offers an overall gain of +2V/V. Table 6 lists example codes for bipolar output voltages.

Reset (RSTVAL) and Clear (CLR) Functions

The MAX5122/MAX5123 DACs feature a clear pin (\overline{CLR}) , which resets the output to a certain value, depending upon how RSTVAL is set. RSTVAL = DGND selects an output of 0, and RSTVAL = V_{DD} selects a midscale output when \overline{CLR} is pulled low.

The $\overline{\text{CLR}}$ pin has a minimum input resistance of $40\text{k}\Omega$ in series with a diode to the supply voltage (V_{DD}). If the digital voltage is higher than the supply voltage for the part, a small input current may flow, but this current will be limited to (V_{CLR} - V_{DD} - 0.5V) / $40\text{k}\Omega$.

Note: Clearing the DAC will also cause the part to exit a software shutdown (PD = 0).

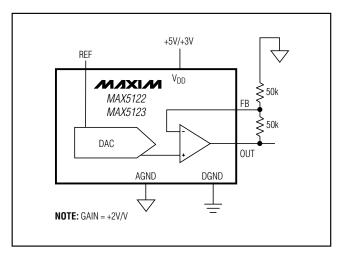


Figure 9. Unipolar Output Circuit Using Internal (+1.25V/+2.5V) or External Reference. With external reference, pull REFADJ to V_{DD}.

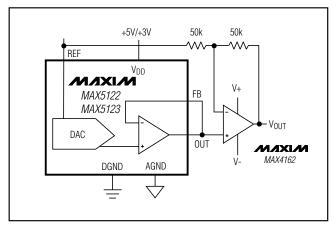


Figure 10. Unity-Gain Bipolar Output Circuit Using Internal (+1.25V/+2.5V) or External Reference. With external reference, pull REFADJ to V_{DD}.

Daisy-Chaining Devices

Any number of MAX5122/MAX5123s may be daisy-chained by simply connecting the serial data output pin (DOUT) of one device to the serial data input pin (DIN) of the following device in the chain (Figure 11).

Another configuration (Figure 12) allows several MAX5122/MAX5123 DACs to share one common DIN signal line. In this configuration, the data bus is common to all devices; data is not shifted through a daisy-chain. However, more I/O lines are required in this configuration, because each IC needs a dedicated $\overline{\text{CS}}$ line.

Table 5. Unipolar Code Table (Figure 9)

| DAC CONTENTS | | ANALOG OUTPUT | | | |
|----------------|---------------|--------------------|-----------|----------------------------------|--|
| MSB LSB | SUB-BIT S0 | INTERNAL REFERENCE | | EXTERNAL REFERENCE | |
| | | MAX5122 | MAX5123 | MAX5122/MAX5123 | |
| 1111 1111 1111 | 0 | +4.99878V | +2.49939V | V _{REF} (4095 / 4096) 2 | |
| 1000 0000 0001 | 0 | +2.50122V | +1.25061V | V _{REF} (2049 / 4096) 2 | |
| 1000 0000 0000 | 0 | +2.5V | +1.25V | V _{REF} (2048 / 4096) 2 | |
| 0111 1111 1111 | 0 | +2.49878V | +1.24939V | V _{REF} (2047 / 4096) 2 | |
| 0000 0000 0001 | 0 | +1.2207mV | +610.35µV | V _{REF} (1 / 4096) 2 | |
| 0000 0000 0000 | 0 | OV | 0V | 0 | |

Table 6. Bipolar Code Table (Figure 10)

| DAC CONTENTS | | ANALOG OUTPUT | | | |
|--------------|---------------|--------------------|-----------|--------------------|---|
| MSB LSB | SUB-BIT S0 | INTERNAL REFERENCE | | EXTERNAL REFERENCE | |
| | | MAX5122 | MAX5123 | MAX5122/MAX5123 | |
| 1111 11 | 11 1111 | 0 | +2.49878V | +1.24939V | VREF [{2 (4095 / 4096)} - 1] |
| 1000 00 | 00 0001 | 0 | +1.2207mV | +610.35µV | V _{REF} [{2 (2049 / 4096)} - 1] |
| 1000 00 | 00 0000 | 0 | OV | OV | VREF [{2 (2048 / 4096)} - 1] |
| 0111 11 | 11 1111 | 0 | -1.2207mV | -610.35µV | V _{REF} [{2 (2047 / 4096)} - 1] |
| 0000 00 | 00 0001 | 0 | -2.49878V | -1.24939V | V _{REF} [{2 (1 / 4096)} - 1] |
| 0000 00 | 00 0000 | 0 | -2.5V | -1.25V | -VREF |

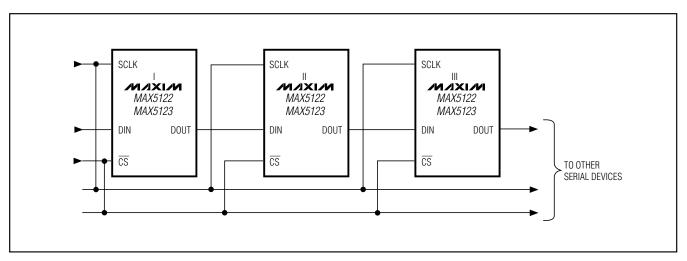


Figure 11. Daisy-Chaining Multiple Devices with the Digital I/Os DIN/DOUT

Using an External Reference with AC Components

The MAX5122/MAX5123 have multiplying capabilities within the reference input voltage range specifications. Figure 13 shows a technique for applying a sinusoidal input to REF, where the AC signal is offset before being applied to the reference input.

Power-Supply and Bypassing Considerations

On power-up, the input and DAC registers are cleared to either zero (RSTVAL = DGND) or midscale (RSTVAL =

 V_{DD}). Bypass the power supply (V_{DD}) with a 4.7 μ F capacitor in parallel with a 0.1 μ F capacitor to AGND. Minimize lead lengths to reduce lead inductance.

Layout Considerations

Digital and AC signals coupling to AGND can create noise at the output. Connect AGND to the highest quality ground available. Use proper grounding techniques, such as a multilayer board with a low-inductance ground plane. Wire-wrapped boards and sockets are not recommended. If noise becomes an issue, shielding may be required.

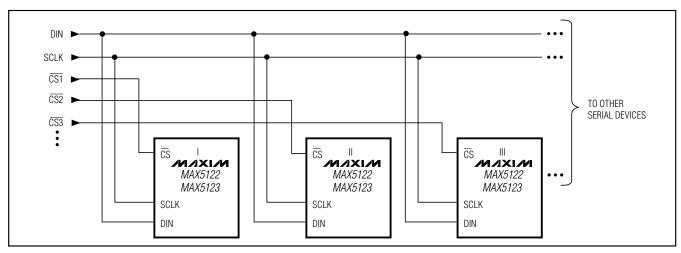


Figure 12. Multiple Devices Share One Common Digital Input (DIN)

+5V/ +3V +5V/+3V MIXXIM AC MAX495 REFERENCE **INPUT** 500mVp-p REF FB DAC OUT MIXIM MAX5122 MAX5123 DGND AGND

Figure 13. External Reference with AC Components

Chip Information

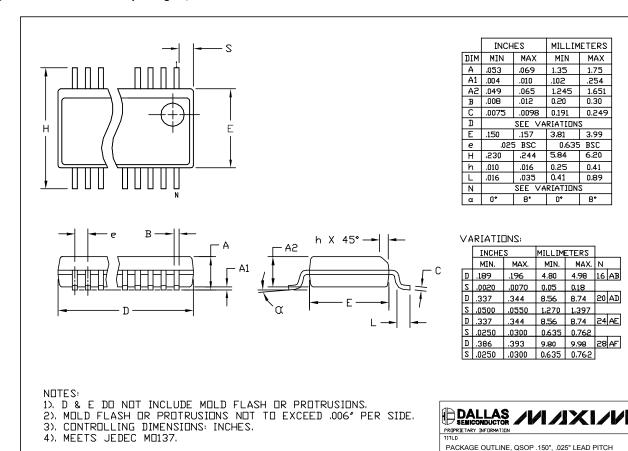
TRANSISTOR COUNT: 3308 SUBSTRATE CONNECTED TO AGND

Package Information

F

21-0055

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to www.maxim-ic.com/packages.)



Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time.